

*Open book exam: Sontag, Mathematical Control Theory, Deterministic finite dimensional systems, 2nd edition, Springer. No other material is allowed.*

There are 5 problems with 10 points each. They are not arranged in degree of difficulty.

- (1) Consider the linear time invariant system  $\dot{x}(t) = Ax(t) + Bu(t)$  starting at  $x(0) = 0$ , where  $A \in \mathbb{R}^{n \times n}$  and  $B \in \mathbb{R}^{n \times m}$ . Let  $\mathcal{R}_t := \{\xi \in \mathbb{R}^n : \exists u \text{ such that } x(t) = \xi\}$ . Show that, for all  $t > 0$ ,  $\mathcal{R}_t = \mathcal{R}(A, B)$ .

- (2) Is the following system stabilizable?

$$\frac{dx}{dt} = \begin{pmatrix} 2 & 1 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} x + \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} u$$

Determine the control law  $u = Kx$  so that the system has its poles at  $-2, -2, -1, -1$ , if the answer is affirmative. Otherwise show that it is impossible. Is it possible to place all poles at  $-2$ ? Justify your answer.

- (3) Assume that  $(A, C) \in \mathcal{S}_{n,p}^{\text{obs}}$ . Show that every symmetric solution,  $K$ , of the following matrix equation

$$-A'K - KA + KLK - C'C = 0$$

is nonsingular.

- (4) Consider the nonlinear system

$$\begin{aligned} \dot{x}_1 &= -x_1 + g(x_2) \\ \dot{x}_2 &= -x_2 + h(x_1) \end{aligned}$$

where  $g(0) = h(0) = 0$ , and  $|g(u)| \leq |u|/2$  and  $|h(u)| \leq |u|/2$ . Show that it is globally asymptotically stable.

- (5) Let  $A = \begin{pmatrix} -\frac{1}{g_1 g_2} & -\frac{1}{\sqrt{g_3 g_2} \sqrt{g_1}} & 0 \\ \frac{1}{\sqrt{g_1 g_2} \sqrt{g_3}} & \frac{1}{g_3 g_2} & \frac{1}{g_3 g_4} \\ 0 & -\frac{1}{\sqrt{g_3 g_4} \sqrt{g_5}} & -\frac{1}{g_5 g_6} - \frac{1}{g_5 g_4} \end{pmatrix}$ ,  $b = \begin{pmatrix} \frac{1}{\sqrt{g_1}} \\ 0 \\ 0 \end{pmatrix} = c$ . Show that

$$c'(sI - A)^{-1}b = \frac{1}{g_1 s + \frac{1}{g_2 + \frac{1}{g_3 s + \frac{1}{g_4 + \frac{1}{g_5 s + \frac{1}{g_6}}}}}} \text{ and assume that } g_i > 0.$$

Is this realization minimal?

Determine a minimal realization for the sequence

$\mathcal{A} = \{1, -1, 2, -5, 14, -42, 131, -417, 1341, -4332, 14041, \dots\}$ . Can  $\mathcal{A}$  be realized in the above form? In this case determine  $g_i$ 's.