

$$1. (a) \frac{\frac{\frac{}{(x_0)} x_0 \doteq x_0}{} \text{refl}}{} \exists I \text{ (with } t := x_0)}{\frac{(x_0) \exists x_1 x_1 \doteq x_0}{} \forall I} \forall x_0 \exists x_1 x_1 \doteq x_0$$

(b)

$$\frac{\frac{\frac{}{(x_0, x_1)} f_1(x_0, x_1) \doteq f_1(x_0, x_1)}{} \text{refl}}{} \exists I \text{ (with } t := f_1(x_0, x_1))}{(x_0, x_1) \exists x_2 f_1(x_0, x_1) \doteq x_2}$$

$$(c) \frac{\frac{\frac{\frac{}{(x_0, x_1)} x_0 \doteq x_1}{} \text{refl}}{} \text{subst (substituting } x_0 \text{ and } x_1 \text{ for } x_2 \text{ in } "f_1(x_0) \doteq f_1(x_2)")}{(x_0, x_1) f_1(x_0) \doteq f_1(x_1)} \rightarrow I_1}{(x_0, x_1) x_0 \doteq x_1 \rightarrow f_1(x_0) \doteq f_1(x_1)} \forall I}{(x_0) \forall x_1 (x_0 \doteq x_1 \rightarrow f_1(x_0) \doteq f_1(x_1))} \forall I \frac{}{\forall x_0, x_1 (x_0 \doteq x_1 \rightarrow f_1(x_0) \doteq f_1(x_1))} \forall I$$

$$(d) \frac{\frac{\frac{\frac{[(x_0, x_2) \forall x_1 (x_1 \doteq x_2)]^3}{(x_0, x_2) x_0 \doteq x_2} \forall E}{(x_0, x_2) f(x_0) \doteq x_0} \text{subst}}{} \exists I}{(x_0) \exists x_2 \forall x_1 (x_1 \doteq x_2)} \exists E_2 \frac{\frac{\frac{[(x_0, x_2) \forall x_1 (x_1 \doteq x_2)]^3}{(x_0, x_2) \exists x_1 f(x_1) \doteq x_0} \forall E}{(x_0, x_2) \exists x_1 f(x_1) \doteq x_0} \exists E_3}{(x_0) \exists x_1 f(x_1) \doteq x_0} \exists E_1 \frac{}{\forall x_0 \exists x_1 f(x_1) \doteq x_0} \forall I_1$$

1(d) could Note: the point of the left-hand subtree is to rename the bound variable " $\exists x_0$ " to " $\exists x_2$ "; we need to do this before the application  $\exists E_3$ , since  $x_0$  is free in the conclusion of  $\exists E_3$ .

2(a)  $\exists x_i (\varphi \vee \psi) \vDash_s (\exists x_i \varphi) \vee (\exists x_i \psi)$  does hold; by soundness, to show this, it suffices to derive  $\exists x_i (\varphi \vee \psi) \vdash_s (\exists x_i \varphi) \vee (\exists x_i \psi)$ .

First, assume that  $x_i$  is free for  $x_i$  in  $\varphi$  and  $\psi$ . (I.e. that  $x_i$  does not occur bound in these.)

Then:

$$\begin{array}{c}
 \frac{\frac{\frac{[(s)\{i\}] \varphi}{(s)\{i\}} \quad \exists I}{(s)\{i\}} \quad \exists I}{(s)\{i\}} \quad \exists I \quad \frac{\frac{[(s)\{i\}] \psi}{(s)\{i\}} \quad \exists I}{(s)\{i\}} \quad \exists I}{(s)\{i\}} \quad \exists I}{(s)\{i\}} \quad \exists I \quad \frac{[(s)\{i\}] \varphi \vee \psi}{(s)\{i\}} \quad \exists I}{(s)\{i\}} \quad \exists I \\
 \frac{\frac{[(s)\{i\}] \varphi \vee \psi}{(s)\{i\}} \quad \exists I \quad \frac{[(s)\{i\}] (\exists x_i \varphi) \vee (\exists x_i \psi)}{(s)\{i\}} \quad \exists I}{(s)\{i\}} \quad \exists I}{(s)\{i\}} \quad \exists I \quad \frac{[(s)\{i\}] (\exists x_i \varphi) \vee (\exists x_i \psi)}{(s)\{i\}} \quad \exists I}{(s)\{i\}} \quad \exists I}{(s)\{i\}} \quad \exists I \quad \frac{[(s)\{i\}] (\exists x_i \varphi) \vee (\exists x_i \psi)}{(s)\{i\}} \quad \exists I}{(s)\{i\}} \quad \exists I} \\
 \frac{(s) \exists x_i (\varphi \vee \psi) \quad (s) (\exists x_i \varphi) \vee (\exists x_i \psi)}{(s) (\exists x_i \varphi) \vee (\exists x_i \psi)} \quad \exists E_1
 \end{array}$$

Here the two instances of  $\exists I$  use the fact that  $\varphi = \varphi[x_i/x_i]$ ,  $\psi = \psi[x_i/x_i]$ , and require the freeness assumption from above.

If  $x_i$  is not free for  $x_i$  in  $\varphi$  or  $\psi$ , then take some variable  $x_j$  not occurring in  $\varphi$  or  $\psi$  (and therefore free for  $x_i$  in them), ~~not~~ replace the hypothesis " $(s) \exists x_i (\varphi \vee \psi)$ " above

with a derivation of  $\exists x_j (\varphi[x_j/x_i]) \vee (\psi[x_j/x_i])$  from  $\exists x_i \varphi \vee \psi$ , and adapt the rest of the derivation to use  $x_j$  where appropriate (as done with  $x_2, x_0$  in 1/d) above).

(b) Again, to show  $(\exists x_i \varphi) \vee (\exists x_i \psi) \vdash \exists x_i (\varphi \vee \psi)$ , it suffices by soundness to show " $\vdash$ "; and again, we assume that  $x_i$  is free for  $x_i$  in  $\varphi, \psi$ , and make a change of variables in case it does not.

$\frac{[(\exists x_i) \varphi] \quad \frac{[(\exists x_i) \psi] \quad \psi}{\exists x_i \psi} \exists E_1}{\exists x_i (\varphi \vee \psi)} \exists E_2$	$\frac{[(\exists x_i) \psi] \quad \psi}{\exists x_i \psi} \exists E_1$
$\frac{(\exists x_i) \varphi \vee (\exists x_i) \psi \quad \exists x_i (\varphi \vee \psi)}{(\exists x_i) \varphi \vee (\exists x_i) \psi} \vee E_1$	$\frac{(\exists x_i) \psi \quad \exists x_i (\varphi \vee \psi)}{(\exists x_i) \psi} \vee E_1$

c) Again, using soundness:

$\frac{[(\exists x_i) \varphi] \quad \varphi}{\exists x_i \varphi} \exists E_1 \quad \frac{[(\exists x_i) \psi] \quad \psi}{\exists x_i \psi} \exists E_1}{\exists x_i \varphi \vee \exists x_i \psi} \vee E_1$	$\frac{[(\exists x_i) \psi] \quad \psi}{\exists x_i \psi} \exists E_1 \quad \frac{[(\exists x_i) \varphi] \quad \varphi}{\exists x_i \varphi} \exists E_1}{\exists x_i (\varphi \vee \psi)} \exists E_1$
$\frac{\exists x_i \varphi \vee \exists x_i \psi \quad \exists x_i (\varphi \vee \psi)}{\exists x_i \varphi \vee \exists x_i \psi} \vee E_1$	

2 (d) " $(\exists x; \psi) \wedge (\exists x; \psi) \leftrightarrow \exists x; (\psi \wedge \psi)$ " does not hold p4  
 in general. Consider the structure  $A := \langle \mathbb{N}; ; \{n \in \mathbb{N} \mid n \text{ odd}\}, \{n \in \mathbb{N} \mid n \text{ even}\} \rangle$ .

F.e.,  $P_1$  and  $P_2$  are unary predicates for the odd and even numbers respectively.

$$\text{Then } A \models (\exists x_0 P_1(x_0)) \wedge (\exists x_0 P_2(x_0)),$$

$$\text{but } A \not\models (\exists x_0 (P_1(x_0) \wedge P_2(x_0)))$$

since no natural number is both even and odd.

3. Set  $\varphi := \forall x_0, x_1, x_2, (x_0 = x_1 \vee x_1 = x_2 \vee x_0 = x_2)$

$$\psi := \forall x_0, x_1, \exists x_2 (\neg(x_2 = x_0) \wedge \neg(x_2 = x_1))$$

By completeness, to show  $\vdash \varphi \vee \psi$ , it suffices to show  $\models \varphi \vee \psi$ , i.e. that  $\llbracket \varphi \vee \psi \rrbracket = 1$  in every interpretation.

So: let  $A$  be any interpretation.

Claim 1: if  $|A|$  has  $< 3$  elements, then  $A \models \varphi$ .

Proof: unravelling the interpretation,

$$A \models \varphi \iff \langle \rangle \in \llbracket \varphi \rrbracket$$

$$\iff \llbracket x_0, x_1, x_2 \mid x_0 = x_1 \vee x_1 = x_2 \vee x_0 = x_2 \rrbracket = A^{\{0,1,2\}}$$

$$\iff \forall a_0, a_1, a_2 \in |A|, \text{ either } a_0 = a_1, a_1 = a_2, \text{ or } a_0 = a_2$$

But if  $|A|$  has  $< 3$  elements, this holds, since ~~for~~ any such  $a_0, a_1, a_2$  cannot all be distinct, so some two must be equal.

3 Cont'd. Claim 2: If  $|A|$  has  $\geq 3$  elements, then  $A \models \neg$ .

Proof. Similarly to above,

$$A \models \neg \Leftrightarrow \forall a_0, a_1 \in |A|, \exists a_2 \in |A|, \text{ s.t. } a_2 \neq a_0 \text{ and } a_2 \neq a_1.$$

But if  $|A|$  has three distinct elements  $b_0, b_1, b_2$ , then given any  $a_0, a_1$ , at least one of  $b_0, b_1, b_2$  must be distinct from  $a_0, a_1$ ; so it gives  $a_2$  as above, so  $A \models \neg$ .

Putting the two claims together, we see that in either case, whether  $|A|$  has  $\geq 3$  or  $< 3$  elements,  $A \models \varphi \vee \neg$ .

So  $\models \varphi \vee \neg$ , so by completeness,  $\vdash \varphi \vee \neg$ .

4. In any structure  $A$ , we have:

$A \models \varphi_{inj}$  iff  $f_1^A$  is ~~an~~ injective,

since unwinding the definition gives

$$\llbracket \varphi_{inj} \rrbracket^A = 1 \Leftrightarrow \forall a_0, a_1 \in |A|, \text{ if } f_1^A(a_0) = f_1^A(a_1), \text{ then } a_0 = a_1,$$

the usual definition of injectivity.

Similarly, ~~Exp~~  $A \models \varphi_{surj}$  iff  $f_1^A$  is surjective, and  $A \models \varphi_{invol}$  iff  $f_1^A$  is an involution (i.e.  $f(f(a)) = a$ , for all  $a \in |A|$ ).

By soundness, if a theory has a model, it is consistent. p 6

We therefore have:

(a)  $\{\varphi_{inj}, \varphi_{surj}\}$  is consistent:

$\langle \mathbb{N}; (-)^2; \rangle$  is a model of it,

since squaring (on  $\mathbb{N}$ ) is injective but not surjective.

(b)  $\{\neg\varphi_{inj}, \varphi_{surj}\}$  is also consistent:

$\langle \mathbb{N}; \lfloor \frac{-}{2} \rfloor; \rangle$  is a model of it, (where  $\lfloor \frac{n}{2} \rfloor$  is the largest integer  $m$  st.  $m \leq \frac{n}{2}$ ), since  $\lfloor \frac{-}{2} \rfloor$  is surj. on  $\mathbb{N}$  but not inj.

(c)  $\{\varphi_{invol}, \neg\varphi_{surj}\}$  is inconsistent:

$$\frac{\frac{\frac{[\neg\varphi_{surj}]^1 \quad \forall x_0 \exists x_1 (f_1(x_1) \doteq x_0)}{\exists x_1 (f_1(x_1) \doteq x_0)} \quad \forall E}{\exists x_1 (f_1(x_1) \doteq x_0)} \quad \exists I \quad (x_1 := f_1(x_0))}{\forall x_0 \exists x_1 (f_1(x_1) \doteq x_0)} \quad \forall I_1}{\neg\varphi_{surj}} \rightarrow E$$

⊥

(d)  $\{\varphi_{invol}, \varphi_{inj}\}$  is again consistent,

since e.g.  $\langle \mathbb{Z}; -; \rangle$  is a model of it (where  $(-)$  denotes unary negation, i.e.  $x \mapsto -x$ ).