

1 (a) $\models (P_1 \rightarrow P_2) \rightarrow P_2$

A countermodel is given by $\llbracket P_1 \rrbracket = 0$, $\llbracket P_2 \rrbracket = 0$.

(b) $P_1 \vee (P_2 \rightarrow P_3) \not\models (P_1 \vee P_2) \rightarrow (P_1 \wedge P_3)$

A countermodel is given by $\llbracket P_1 \rrbracket = 1$, $\llbracket P_2 \rrbracket = 0$, and $\llbracket P_3 \rrbracket$ arbitrary.

(c) $P_1 \vee P_2 \not\models ((P_1 \rightarrow P_3) \vee (P_2 \rightarrow P_3)) \rightarrow P_3$

A countermodel is given by $\llbracket P_1 \rrbracket = 1$, $\llbracket P_2 \rrbracket = 0$ and $\llbracket P_3 \rrbracket = 0$.

2 (a) $\models x_2 \exists x_3 (P_2(\underline{x}_1, x_2) \rightarrow x_2 = f_2(\underline{x}_1, x_3))$

the only free variable is x_1 .

(b) $((\models x_1 \exists x_2 P_1(x_1, x_2)) \wedge P_2(f_1(\underline{x}_1, \underline{x}_5)))$

$\rightarrow \models x_1 (\exists x_2 P_1(x_1, x_2) \wedge P_2(f_1(\underline{x}_1, \underline{x}_5)))$

The free variables are x_1 and x_5

3 (a)
$$\frac{[\neg P_1]^2 [P_1]^1}{\perp}$$

$$\frac{\neg P_1 \vee P_2}{\frac{P_2}{P_1 \rightarrow P_2}} [P_2]^3 E_{\vee, 2, 3}$$

(b) We give two different derivations

$$\begin{array}{c}
 \frac{\frac{\frac{[\neg(\neg P_1 \vee P_2)]^1}{\frac{\neg P_1 \vee P_2}{\frac{[\neg P_1]^2}{\frac{[\neg(\neg P_1 \vee P_2)]^1}{\frac{\neg P_1 \vee P_2}{\frac{[\neg P_1]^3}{\frac{[\neg(\neg P_1 \vee P_2)]^1}{\frac{\neg P_1 \vee P_2}{\frac{\perp}{\frac{P_1 \rightarrow P_2}{\frac{P_1}{\frac{P_2}{\frac{\perp}{\neg P_1 \vee P_2}}}}}}}}}}}}}{I_{\vee, n}}}{E_{\rightarrow}}}{I_{\rightarrow, 2}} \\[10pt]
 \frac{\frac{P_1 \rightarrow P_2}{P_2}}{RAA, 1} \\[10pt]
 \frac{\frac{\frac{\frac{P_1 \rightarrow P_2}{P_2}}{P_1}}{P_1}}{RAA, 3}}{E_{\rightarrow}}
 \end{array}$$

$$\begin{array}{c}
 \frac{P_1 \rightarrow P_2}{P_2} \frac{[P_1]^2}{E_{\rightarrow}} \\[10pt]
 \frac{\frac{[\neg(\neg P_1 \vee P_2)]^1}{\frac{\neg P_1 \vee P_2}{\frac{[\neg P_1]^3}{\frac{[\neg(\neg P_1 \vee P_2)]^1}{\frac{\neg P_1 \vee P_2}{\frac{\perp}{\frac{P_1 \rightarrow P_2}{\frac{P_1}{\frac{P_2}{\frac{\perp}{\neg P_1 \vee P_2}}}}}}}}}}}{I_{\vee, n}}}{E_{\rightarrow}} \\[10pt]
 \frac{\frac{\frac{P_1 \rightarrow P_2}{P_2}}{P_1}}{I_{\rightarrow, 2}} \\[10pt]
 \frac{\frac{[\neg(\neg P_1 \vee P_2)]^1}{\frac{\neg P_1 \vee P_2}{\frac{[\neg P_1]^2}{\frac{[\neg(\neg P_1 \vee P_2)]^1}{\frac{\neg P_1 \vee P_2}{\frac{\perp}{\frac{P_1 \rightarrow P_2}{\frac{P_1}{\frac{P_2}{\frac{\perp}{\neg P_1 \vee P_2}}}}}}}}}}}{I_{\vee, p}}}{E_{\rightarrow}} \\[10pt]
 \frac{\frac{\frac{P_1 \rightarrow P_2}{P_2}}{P_1}}{RAA, 1}
 \end{array}$$

14 see Carlström's course

[5] We can take $\varphi_0 = P_1$, $\varphi_1 = P_2$ and $\varphi_2 = \neg(P_1 \wedge P_2)$

By soundness, to show theories are consistent it is enough to give a model.

- $\{\varphi_0, \varphi_1\}$ is consistent, a model is given by $\llbracket P_1 \rrbracket = 1, \llbracket P_2 \rrbracket = 1$
- $\{\varphi_0, \varphi_2\}$ is consistent, a model is given by $\llbracket P_1 \rrbracket = 1, \llbracket P_2 \rrbracket = 0$
- $\{\varphi_1, \varphi_2\}$ is consistent, a model is given by $\llbracket P_1 \rrbracket = 0, \llbracket P_2 \rrbracket = 1$

However $\{\varphi_0, \varphi_1, \varphi_2\}$ is not consistent

$$\frac{\begin{array}{c} P_1 \quad P_2 \\ \hline \neg(P_1 \wedge P_2) \end{array}}{\bot} \text{ shows that } \varphi_0, \varphi_1, \varphi_2 \vdash \bot .$$

[6] Let's suppose $\Gamma \vdash \varphi$, then $\frac{\neg\varphi \quad \varphi}{\bot} E \rightarrow$ shows that $\Gamma_0(\neg\varphi) \vdash \bot$

Conversely, we suppose $\Gamma \cup \{\neg\varphi\} \vdash \bot$

$$\text{then } \frac{\begin{array}{c} [\neg\varphi]^1 \quad \Gamma \\ \vdots \\ \bot \end{array}}{\varphi} \text{ RAA}_1 \text{ where the RAA discharge all occurrences of } \neg\varphi$$

shows that $\Gamma \vdash \varphi$.

7) (a) We give a derivation,

$$\frac{\frac{P_1(x_0) \rightarrow P_2(x_0)}{\exists x_0 P_1(x_0) \rightarrow P_2(x_0)} I_{\exists}}{\exists x_0 (P_1(x_0) \rightarrow P_2(x_0))} E_{\exists,1}$$

(b) We give a countermodel.

$$|A| = \{a, b\} \quad \llbracket P_1(a) \rrbracket = 1 \quad \llbracket P_1(b) \rrbracket = 0 \quad \text{and the valuation arbitrary.}$$

$$\llbracket P_2(a) \rrbracket = 0 \quad \llbracket P_2(b) \rrbracket = 1$$

$$\text{then } \llbracket P_1(a) \vee P_2(a) \rrbracket = 1 \text{ and } \llbracket P_1(b) \vee P_2(b) \rrbracket = 1$$

$$\text{implies } A \models \forall x_0 (P_1(x_0) \vee P_2(x_0))$$

$$\text{but } A \not\models \forall x_0 P_1(x_0) \quad \text{as } \llbracket P_1(b) \rrbracket = 0$$

$$A \not\models \forall x_0 P_2(x_0) \quad \text{as } \llbracket P_2(a) \rrbracket = 0$$

$$\text{hence } A \not\models (\forall x_0 P_1(x_0)) \vee (\forall x_0 P_2(x_0))$$

By soundness, $\forall x_0 (P_1(x_0) \vee P_2(x_0)) \vdash (\forall x_0 P_1(x_0)) \vee (\forall x_0 P_2(x_0))$
cannot be derived.

18) By soundness it is enough to give a model.

We take $|A| = \{a, b\}$ $\left\{ \begin{array}{l} \llbracket f_1(a) \rrbracket = b \text{ and } \llbracket f_1(b) \rrbracket = a \\ \text{and the valuation arbitrary.} \end{array} \right. \left\{ \begin{array}{l} \llbracket P_1(a) \rrbracket = 1 \text{ and } \llbracket P_1(b) \rrbracket = 0 \\ \end{array} \right.$

- $\llbracket a = a \vee a = b \rrbracket = 1$ and $\llbracket b = a \vee b = b \rrbracket = 1$
so $A \models \exists x_1 \exists x_2 \forall x_3 (x_3 = x_1 \vee x_3 = x_2)$

- $\llbracket P_1(a) \rightarrow \neg P_1(f_1(a)) \rrbracket = 1$ as $\llbracket \neg P_1(f_1(a)) \rrbracket = \llbracket \neg P_1(b) \rrbracket = 1$
 $\llbracket P_1(b) \rightarrow \neg P_1(f_1(b)) \rrbracket = 1$ as $\llbracket P_1(b) \rrbracket = 0$
so $A \models \forall x_1 (P_1(x_1) \rightarrow \neg P_1(f_1(x_1)))$

- $\llbracket P_1(a) \rrbracket = 1$, so $A \models \exists x_1 P_1(x_1)$.

$$\boxed{9} \quad \frac{\frac{\frac{\frac{\exists x_o P_1(x_o) \rightarrow \exists x_o P_2(x_o)}{\exists x_o P_1(x_o)} \text{ I}_3}{\exists x_o P_1(x_o)} \text{ E} \rightarrow \frac{\frac{P_1(x_o)}{[P_2(x_o)]^1} \text{ I}_3}{P_1(x_o) \rightarrow P_2(x_o)} \text{ I}_3}{\exists x_o (P_1(x_o) \rightarrow P_2(x_o))} \text{ E}_{3,1}}$$

gives a derivation \mathcal{D}_1 of $\exists x_o P_1(x_o) \rightarrow \exists x_o P_2(x_o), P_1(x_o) \vdash \exists x_o (P_1(x_o) \rightarrow P_2(x_o))$

$$\frac{\frac{\frac{\neg P_1(x_o) \quad [P_1(x_o)]^1}{\frac{\downarrow}{P_2(x_o)} \text{ E}_\perp}{\text{I} \rightarrow, 1}}{P_1(x_o) \rightarrow P_2(x_o)} \text{ I}_3}{\exists x_o (P_1(x_o) \rightarrow P_2(x_o))}$$

gives a derivation \mathcal{D}_2 of $\neg P_1(x_o) \vdash \exists x_o (P_1(x_o) \rightarrow P_2(x_o))$

The full derivation is given by :

$$\begin{array}{c}
 \frac{\frac{\frac{[\neg(\rho_1(x_0) \vee \neg\rho_1(x_0))]}{P_1(x_0) \vee \neg P_1(x_0)} \stackrel{[P_1(x_0)]}{\text{I}\vee, E}}{\perp} \stackrel{I\rightarrow, 2}{\text{E}\rightarrow}}{\neg P_1(x_0)} \stackrel{I\vee, 2}{\text{E}\rightarrow} \\
 \frac{\frac{\frac{[\neg(\rho_1(x_0) \vee \neg\rho_1(x_0))]}{P_1(x_0) \vee \neg P_1(x_0)} \stackrel{I\vee, 2}{\text{E}\rightarrow}}{\perp} \stackrel{RAA, 1}{\text{E}\rightarrow}}{P_1(x_0) \vee \neg P_1(x_0)} \\
 \frac{\exists x_0 (\rho_1(x_0) \rightarrow \exists x_1 \rho_2(x_0)) \quad [\rho_1(x_0)]}{\exists x_0 (\rho_1(x_0) \rightarrow \rho_2(x_0))} \quad \frac{\exists x_0 (\rho_1(x_0) \rightarrow \rho_2(x_0))}{\exists x_0 (\rho_1(x_0) \rightarrow \rho_2(x_0))} \stackrel{D_1}{\text{D}} \stackrel{D_2}{\text{D}} \\
 \frac{\exists x_0 (\rho_1(x_0) \rightarrow \rho_2(x_0))}{\exists x_0 (\rho_1(x_0) \rightarrow \rho_2(x_0))} \stackrel{E_V}{\text{E}\vee}
 \end{array}$$

10 (a) True.

If $\Gamma_1 \cap \Gamma_2 \vdash \perp$ then, as $\Gamma_1 \cap \Gamma_2 \subseteq \Gamma_1$, $\Gamma_1 \vdash \perp$.

But as Γ_1 is consistent $\Gamma_1 \not\vdash \perp$ so $\Gamma_1 \cap \Gamma_2 \not\vdash \perp$ and $\Gamma_1 \cap \Gamma_2$ is consistent.

(b). False.

Take $\Gamma_1 = \{\rho_1\}$ and $\Gamma_2 = \{\neg\rho_1\}$,

$\llbracket \rho_1 \rrbracket = 1$ gives a model to Γ_1 , and $\llbracket \rho_1 \rrbracket = 0$ gives a model to Γ_2 and by soundness Γ_1, Γ_2 are consistent.

But $\Gamma_1 \cup \Gamma_2 = \{\rho_1, \neg\rho_1\}$ is not consistent, $\frac{\neg\rho_1 \quad \rho_1}{\perp} \text{I}\rightarrow$ shows that $\Gamma_1 \cup \Gamma_2 \vdash \perp$.

(c) True.

If $\bigcup_{n \in \mathbb{N}} \Gamma_n$ is inconsistent, then a proof of \perp with hypotheses in $\bigcup_{n \in \mathbb{N}} \Gamma_n$, only uses a finite number of hypotheses that we denote by $\varphi_0, \varphi_1, \dots, \varphi_k$.

Each φ_i belongs to some Γ_{n_i} and by taking $N := \max\{n_0, \dots, n_k\}$ each φ_i belongs to Γ_N (as $\Gamma_{n_i} \subseteq \Gamma_N$).

So we can derive \perp from Γ_N and Γ_N is not consistent.

(d) False.

Let Γ_1, Γ_2 as in (b). As Γ_1 is consistent, we can find Γ_1^* a maximally consistent extension of Γ_1 , and similarly Γ_2^* a maximally consistent extension of Γ_2 .

But, as $\Gamma_1^* \cup \Gamma_2^* \supseteq \Gamma_1 \cup \Gamma_2$, $\Gamma_1^* \cup \Gamma_2^*$ is not consistent and so not maximally consistent.

[11] We denote $t_0 = f_1$ and $t_{n+1} = f_2(t_n)$ for $n \in \mathbb{N}$

We can show by induction that $\|t_n\|^{w,v} = n$ for all $n \in \mathbb{N}$.

Suppose $\text{Th}(d, v) \vdash \exists x_0 \varphi$

then by soundness we have $d, v \models \exists x_0 \varphi$

and so there exists some $m \in \mathbb{N}$ such that $d, v[x_0 \mapsto t_m] \models \varphi$

and this implies $d, v \models \varphi[t_m/x_0]$

As t_m is closed, this shows that $\text{Th}(d, v)$ has the existence property.

12 (a) We let $t_1 := x_0$, and $t_{n+1} := f_2(x_0, t_n)$ for $n \geq 1$.

and we take $\varphi_n = P_1(t_n, f_1)$ for all $n \geq 1$.

(t_n represents $\underbrace{x_0 + \dots + x_0}_{n \text{ times}}$ so φ_n expresses " $n \cdot x_0 < 1$ ")

(b) We show that the theory has a model using compactness.

Let Γ_0 be a finite subtheory of $\text{Th}(\emptyset) \cup \{\varphi_0, \varphi_1, \dots\}$

Then Γ_0 is contained in $\text{Th}(\emptyset) \cup \{\varphi_0, \dots, \varphi_N\}$ for some $N > 0$.

It is thus enough to give a model of $\text{Th}(\emptyset) \cup \{\varphi_0, \dots, \varphi_N\}$

We claim that $\emptyset, v[x_0 \mapsto \frac{1}{N+1}] \models \text{Th}(\emptyset) \cup \{\varphi_0, \dots, \varphi_N\}$

$\emptyset, v[x_0 \mapsto \frac{1}{N+1}] \models \text{Th}(\emptyset)$ as the formulas in $\text{Th}(\emptyset)$ have no free variables

$\emptyset, v[x_0 \mapsto \frac{1}{N+1}] \models \varphi_0$ as $\frac{1}{N+1} > 0$

$\emptyset, v[x_0 \mapsto \frac{1}{N+1}] \models \{\varphi_1, \dots, \varphi_N\}$ as $\frac{1}{N+1} < \frac{1}{n}$ for $n = 1 \dots N$

So $\text{Th}(\emptyset) \cup \{\varphi_0, \dots, \varphi_N\}$ has a model and Γ_0 also, as wanted.

(c) $\emptyset, v \models \varphi_0$ gives $v(x_0) > 0$

and for $n > 0$, $\emptyset, v \models \varphi_n$ gives $v(x_0) < \frac{1}{n}$

Hence we would have $v(x_0) > 0$ and $v(x_0) < \frac{1}{n}$ for all $n > 0$.

This is not possible as $\{x \in \mathbb{Q} \mid x > 0 \text{ and } \forall n > 0, x < \frac{1}{n}\} = \emptyset$.